Type	Hits	Search Text	DBs	Time Stamp
BRS	1097	(250/359.1 or 250/341.8 or 250/339.11 or 250/559.01).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	586	(162/198 or 162/50).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	752	(342/278 or 342/195).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	103	(356/478).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	2285	(162/198 or 162/50 or 162/263 or 162/dig.10-dig.11 or 162/183 or 162/212 or 162/252 or 162/259 or 162/253 or 162/262 or 162/336 or 162/471 or 162/469).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	42	stationary adj array with sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	9	(stationary adj array with sensor) and paper	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1023	paper adj manufacturing adj process	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	3422	kalman adj filter	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1025	(702/172 or 702/183 or 702/189).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1414	(702/97 or 702/104 or 702/155-159 or 702/170).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
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BRS	3604	(702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	4907	((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	71	(((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.)) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	3	(((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.)) and (kalman adj filter) and convolution	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	0	((((((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.)) and (kalman adj filter)) and convolution) and error) and senosr	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1	((((((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.)) and (kalman adj filter)) and convolution) and error) and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	125	(700/130 or 700/140).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	203	(708/5 or 708/814).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	231	(73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	778	(250/559.19 or 250/559.4).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1337	((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	0	((((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.)) and (data adj fusion)) and kalman	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	7580	array adj sensors	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1	((((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.)) and (data adj fusion)) and filter	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	56	(array adj sensors) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	0	(((((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.)) and (data adj fusion)) and filter) and adaptive	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	49	(stationary adj sensor) and (scanning adj sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	0	((US-4931982-$).did.) and sensor	USPAT	06/08/04
BRS	0	((US-4931982-$).did.) and detector	USPAT	06/08/04
BRS	111	(700/129).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	0	((US-4931982-$).did.) and sensor	USPAT	06/08/04
BRS	0	((US-4931982-$).did.) and stationary	USPAT	06/08/04
BRS	0	(((US-4931982-$).did.) and output) and array	USPAT	06/08/04
BRS	1954	array adj sensor	USPAT	06/08/04
BRS	0	(array adj sensor) and (data adj fusing)	USPAT	06/08/04
BRS	4	(array adj sensor) and (data same fusing)	USPAT	06/08/04
BRS	4	((array adj sensor) and (data same fusing)) and sensor	USPAT	06/08/04
BRS	0	((((array adj sensor) and (data same fusing)) and sensor) and scanning) and stationary	USPAT	06/08/04
BRS	0	((US-4931982-$).did.) and frequency	USPAT	06/08/04
BRS	0	((US-4931982-$).did.) and speed	USPAT	06/08/04
BRS	0	((US-4931982-$).did.) and velocity	USPAT	06/08/04
BRS	0	((US-4931982-$).did.) and odometer	USPAT	06/08/04
BRS	2366	odometer	USPAT	06/08/04
BRS	106	odometer and kalman adj filter	USPAT	06/08/04
BRS	43	(odometer and kalman adj filter) and array	USPAT	06/08/04
BRS	42	((odometer and kalman adj filter) and array) and sensors	USPAT	06/08/04
BRS	37	(((odometer and kalman adj filter) and array) and sensors) and cross	USPAT	06/08/04
BRS	22	((((odometer and kalman adj filter) and array) and sensors) and cross) and (cross same section)	USPAT	06/08/04
BRS	0	(((((odometer and kalman adj filter) and array) and sensors) and cross) and (cross same section)) and coordinate) and (least adj mean)	USPAT	06/08/04
BRS	411	synthetic and kalman	USPAT	06/08/04
BRS	0	((US-4931982-$).did.) and synthetic	USPAT	06/08/04
BRS	1	((stationary adj array with sensor) and paper) and synthesiz$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1	(paper adj manufacturing adj process) and kalman adj filter	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	2	(kalman adj filter) and (paper adj manufacturing)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	2	(kalman adj filter) and (stationary adj array same sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	8	(kalman adj filter) and (stationary with array same sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	2	(((((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.)) and (kalman adj filter)) and convolution) and error	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1	(((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.)) and (data adj fusion)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	2	((array adj sensors) and (kalman adj filter)) and scanning near sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	3	((stationary adj sensor) and (scanning adj sensor)) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1	(US-4931982-$).did.	USPAT	06/08/04
BRS	1	((US-4931982-$).did.) and scanning	USPAT	06/08/04
BRS	3	((700/129).ccls.) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	06/08/04
BRS	1	((US-4931982-$).did.) and output	USPAT	06/08/04
BRS	1	((US-4931982-$).did.) and output	USPAT	06/08/04
BRS	3	(((array adj sensor) and (data same fusing)) and sensor) and scanning	USPAT	06/08/04
BRS	21	(((((odometer and kalman adj filter) and array) and sensors) and cross) and (cross same section)) and coordinate	USPAT	06/08/04
BRS	29	(synthetic and kalman) and (mean adj square)	USPAT	06/08/04
BRS	1	((US-4931982-$).did.)	USPAT	06/08/04